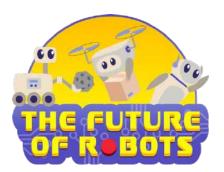


RoboMission Senior Game Rules Season 2025



The Future of Robots Rocket Assembly

Official Game Rules for the WRO International Final. Version: January 15th 2025 (Note: Rules for local WRO events may vary!)

WRO International Premium Partner



WRO International Gold Partners



Table of Contents

1. Int	roduction	
2. Ga	ame Field	
3. Ga	ame Objects, Positioning, Randomization	
3.1	Assemble the rocket nose	
3.2	Integrate rocket sections	9
3.3	Load the rocket	11
3.4	Check systems	
3.5	Close the hatches	
3.6	Bonus for barriers	
4. Sc	oring Sheet	15

Important information for reading this document:

- The general rules have changed drastically for 2025. Make sure to read them entirely.
- These game rules are made for local and national competitions.
- National Organizers in WRO countries are allowed to simplify the missions.
- For the International Final, one extra mission will be released on October 8th 2025. The extra challenge will work with the same game mat and brick set. It is not mandatory to do this extra mission to participate in the event.
- Because of possible surprise rules and the extra mission for the International Final, the game field may contain areas and markings that are not used at local or national events.
- For greater clarity, the robot missions are explained in multiple sections. But the teams can decide which missions they will do and which order.
- The game missions have easy and more complicated tasks. This makes the competition suitable for beginning and more experience teams. It is not necessary to solve all missions to enjoy a WRO participation.
- General information on game table setup and fixing of game objects on the field you find in the WRO RoboMission General Rules, chapter 7.

We wish everyone much success and a lot of fun with our WRO 2025 challenges!

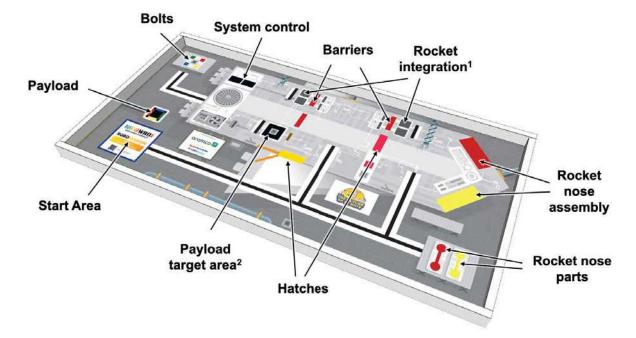
Your team of World Robot Olympiad Association

1. Introduction

Launching rockets into space is crucial for advancing society by enabling scientific exploration, satellite deployment, global communications, and the development of new technologies. It allows humanity to better understand the universe, monitor Earth's environment, and improve global connectivity. Building and assembling rockets requires extreme precision, as even minor errors in design or construction can lead to catastrophic failures. Every component must be accurately aligned, from the fuel systems to navigation controls, to ensure a successful launch. Robots play a vital role in this process, supporting tasks such as welding, drilling, and assembling intricate parts with unparalleled accuracy and consistency, reducing human error, and speeding up the manufacturing process. This automation ensures higher quality, safety, and efficiency in rocket assembly.

Can your robot help assembling the rocket and make it ready for a space launch?

2. Game Field



The following graphic shows the game field with the different areas.

1) Rocket integration: Positions of corresponding marking blocks are on the other side of the barriers.

2) Payload target area: Position of marking block is on the right side next to the target area.

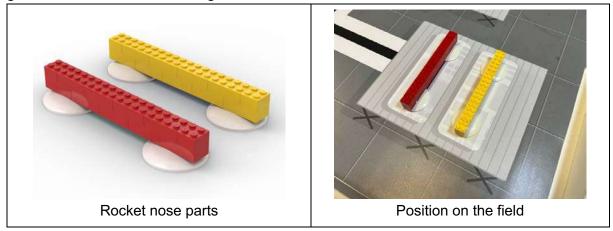
If the table is larger than the game mat, place the mat against the wall with the two sides closer to the start area (in the picture: left and bottom side).



3. Game Objects, Positioning, Randomization

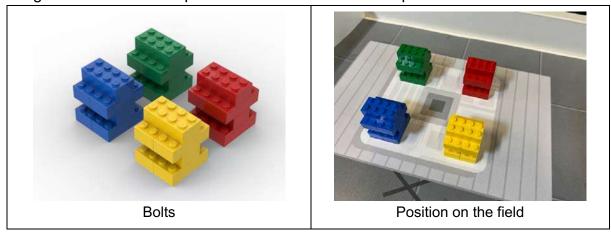
Rocket nose parts

There are **2 rocket nose parts (1x red, 1x yellow)** on the field. The position on the game field is in the bottom right corner.



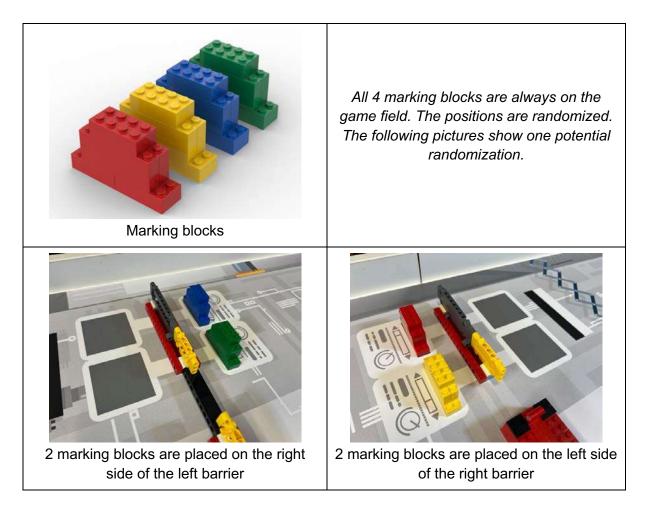
Bolts and marking blocks for rocket integration

There are **4 bolts (1x green, 1x blue, 1x yellow, 1x red)** on the field. The position on the game field is in the top left corner on the coloured squares.



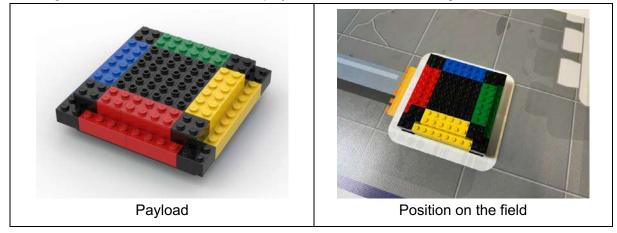


There are **4 marking blocks (1x green, 1x blue, 1x yellow, 1x red)** on the field. The positions are grey rectangles on the upper end of the field next to the barriers. Which colour fills which position is randomized.



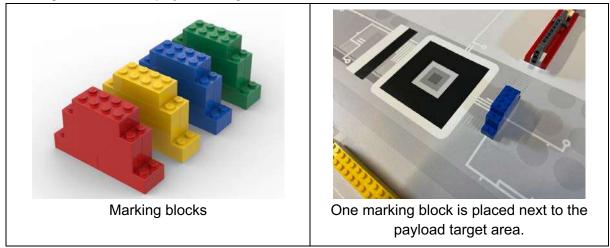
Payload with marking block

There is **1 payload** on the field. The position on the game field is directly next to the starting area. The orientation of the payload is marked on the game field.



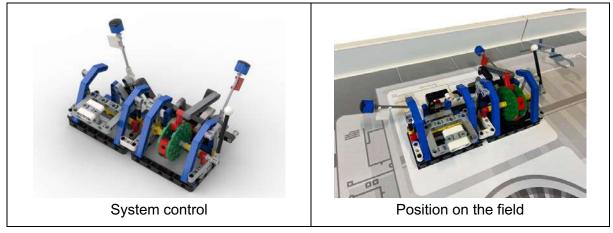


There are **4** additional marking blocks (1x green, 1x blue, 1x yellow, 1x red) but only one is chosen randomly and placed on the field. The position is the brown rectangle next to the payload target area.

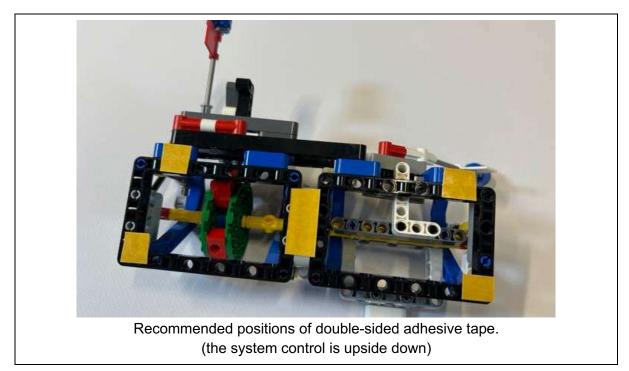


System control

There is **1 system control** on the field. The position is marked by two black rectangles at the left end of the rocket. The system console is fixed on the game field with double-sided adhesive tape. The white flag on the left pole points to the left. The red flag on the right pole points downwards / to the back.

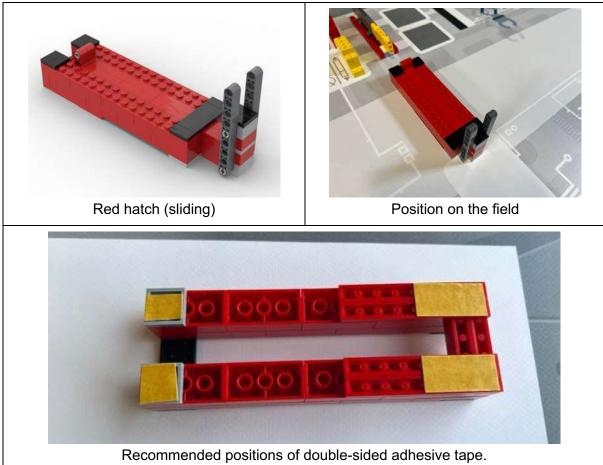


WORLD ROBOT OLYMPIAD TM WRO 2025 – RoboMission – Senior

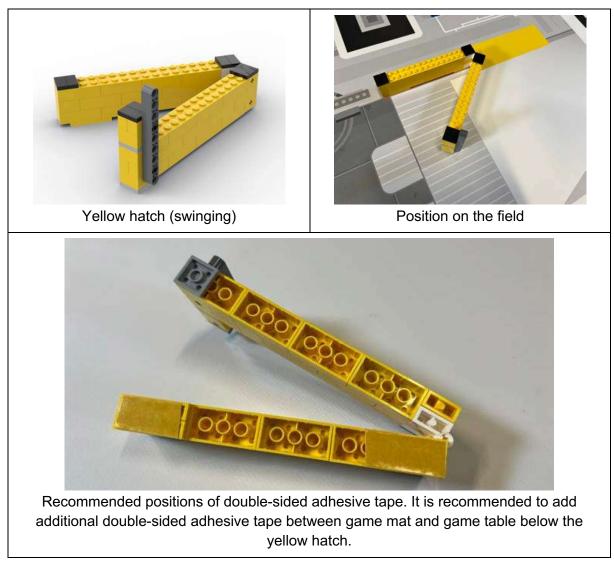


Hatches

There are **2 hatches (1x yellow, 1x red)** on the field. The positions are marked in red and orange. The hatches are fixed on playing field with double-sided adhesive tape.

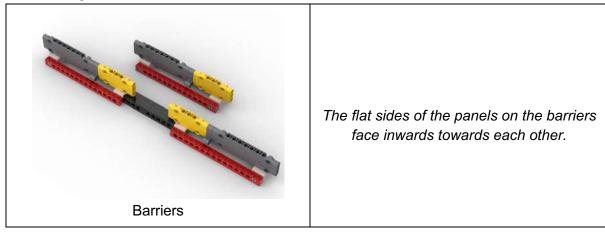




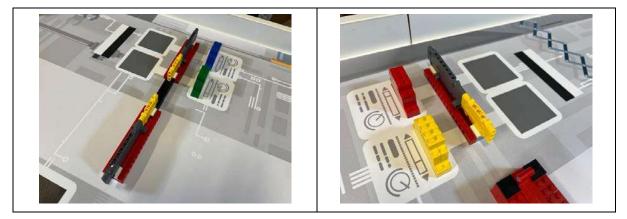


Barriers

There are **2 barriers (1x short, 1x long)** on the field. The positions are marked with red rectangles.





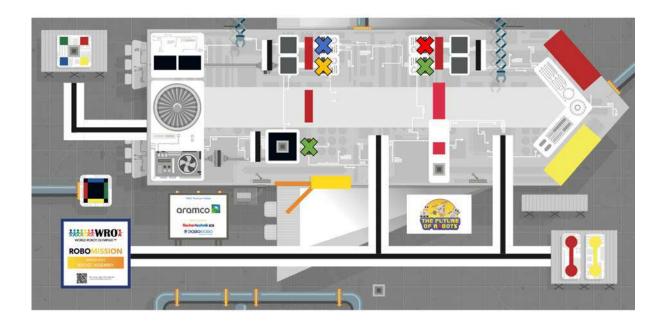


Summary randomization

On this field, the following objects are randomly placed in each round:

- 4 marking blocks for rocket integration
- 1 marking block for the payload integration

You can see one possible randomization here (only randomized objects are marked):



Robot Missions

3.1 Assemble the rocket nose

Two rocket nose parts are placed in the bottom right corner of the game field. The rocket nose can be assembled by bringing the two nose parts to the correct coloured areas. Full points are awarded if the parts are completely and upright in the correct coloured area.

• <u>Definition "completely in":</u> Completely means that the game object is touching the corresponding area only.

			Each	Max.
The nose part is completely and upright in the <u>correct coloured</u> rocket nose target area.			10	20
The nose part is completely and upright in the <u>wrong-coloured</u> rocket nose target area.			5	
10 points (completely inside and in upright position)	0 points (partly outside of area)	(part	0 points ly is outside	
0 points (not in upright position)	5 points (fully in and upright, but wrong colour)		0 points (not uprig	

• Only one element scores points per target area.

3.2 Integrate rocket sections

The rocket is divided in three parts by the barriers. The matching bolts must be used to firmly connect the parts together. The marking blocks on the other side of the barriers show which bolt is needed.

<u>Definition "completely in"</u>: Completely means that the game object is touching the corresponding area only.

- Only one element scores points per target area.
- Each Max. Bolt is completely in the rocket integration area and its colour is 12 48 matching the colour of the corresponding marking block 5 Bolt is partly touching any rocket integration area or completely in but not matching the colour of the corresponding marking block 12 points 12 points (correct coloured bolt completely in area) (Bolt does not have to be upright) 5 points 5 points (bolt partly in area) (completely in but wrong colour) 5 points 0 points (partly in and wrong colour) (bolt not touching target area)
- The white borders around the rocket integration areas are <u>not</u> part of the areas.

3.3 Load the rocket

The job of a rocket is to transport cargo into space. Bring the payload into the rocket and make sure it is placed correctly.

- <u>Definition "completely in"</u>: Completely means that the game object is touching the corresponding area only.
- The white border around the payload area is <u>not</u> part of the area.

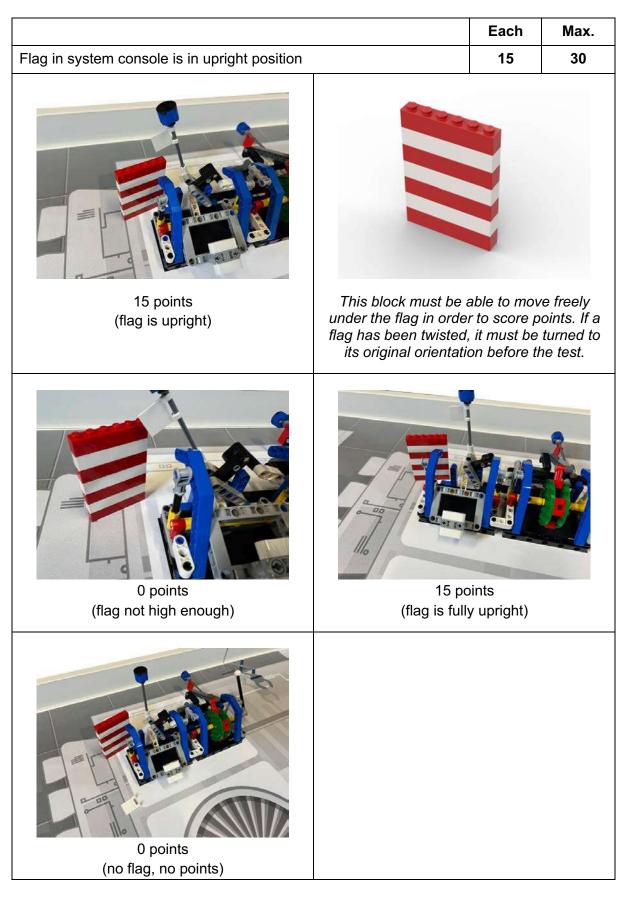
			Each	Max.
Payload is fully in the payload area and has the correct orientation			28	28
Payload is partly touching the payload area (no matter which orientation) <u>or</u> fully in but has the wrong orientation			14	
28 points (completely inside and correct orientation)	14 points (completely inside, but wrong orientation)	corr side block as the the si the aligr re	Hint: The payload is rrectly orientated if the de facing the marking ck has the same colour ne marking block. Due to size of the payload and ne target area, a clear gnment can always be recognized when the load is completely in the target area.	
14 points (only partly inside, orientation not relevant)	14 points (only partly inside, orientation not relevant)	(not	0 points touching tar	

3.4 Check systems

Before a rocket can be launched, all systems must be tested. This test is carried out on the system console. The two operations on the system console are interlocked and must be operated in the correct order. The first operation is pushing down on the left side and the second operation is pulling the lever on the right side. The result is checked by the positions of the flags.

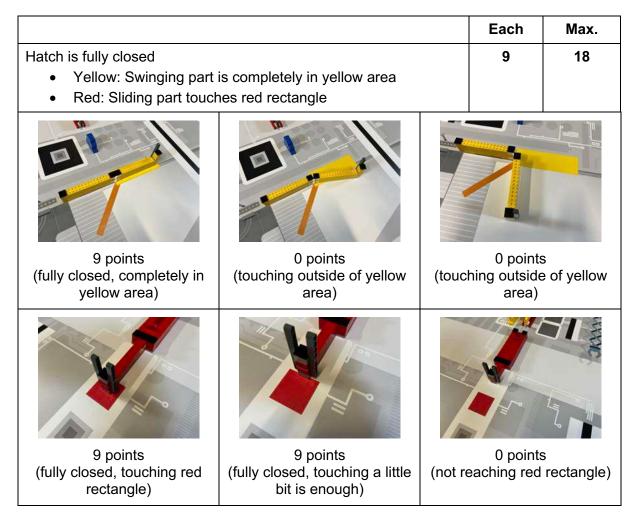
WORLD ROBOT OLYMPIAD TM

WRO 2025 - RoboMission - Senior



3.5 Close the hatches

Two hatches are on the field. The yellow one is a swinging hatch. The red one is a sliding hatch. Both hatches score points when they are fully closed. The following table shows when hatches are considered closed.



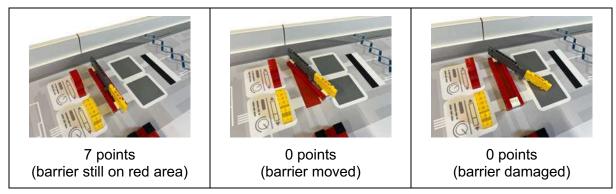
3.6 Bonus for barriers

Working on a rocket requires absolute precision. It is therefore not permitted to move the two barriers. The playing field does not provide any tolerances for moving. Minimal shifts that may have been caused by imprecise positioning before the run, have to be counted in favour of the team in case of doubt. Final decision of this is with the judge.

- Definition "damaged": Any situation that means that the game object is not exactly like at the start of the run, e.g. a brick fell off.
- Definition "moved": The game object is considered as moved if a part of the game object is touching the mat outside of the red areas.

	Each	Max.
Barrier is not damaged or moved	7	14





4. Scoring Sheet

Team name:		Round:			
Tasks	Each	Max.	#	Total	
Assemble the rocket nose					
The nose part is completely and upright in the <u>correct coloured</u> rocket nose target area.	10	20			
The nose part is completely and upright in the <u>wrong-coloured</u> rocket nose target area.	5				
Integrate rocket sections					
Bolt is completely in the rocket integration area <u>and</u> its colour is matching the colour of the corresponding marking block	12	48			
Bolt is partly touching any rocket integration area <u>or</u> completely in but not matching the colour of the corresponding marking block	5				
Load the rocket					
Payload is fully in the payload area <u>and</u> has the correct orientation	28	28			
Payload is partly touching the payload area (no matter which orientation) <u>or</u> fully in but has the wrong orientation	14				
Check systems					
Flag in system console is in upright position	15	30			
Close the hatches					
Hatch is fully closedYellow: Swinging part is completely in yellow areaRed: Sliding part touches red rectangle	9	18			
Bonus for barriers					
Barrier is not damaged or moved	7	14			
Maximum Score		158			
Total Score in this ru			this run		
	Tir	ne in full s	econds		